

Macroeconomic Shocks and their Propagation Under Rational Inattention

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Behavioral Macro Workshop 2026
June 26, 2026

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- habits, nominal rigidities, inv. adj. costs
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“My own view is that the best of these models ought to be regarded as proxies for better, harder-to-construct models ...”

— Sims (1998, p.319)

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Rational inattention approach

[Sims, Maćkowiak-Wiederholt, Afrouzi-Yang]

- signal-extraction problems
- *endogenous*
- one source of slow adj., many actions

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This paper confronts the two approaches in a **medium-scale DSGE**

- **Challenges**

- No medium-scale **RI** model (investment + pricing decisions)
- Isolate the competing mechanisms: **RI** vs **NK**

Contributions & key ideas

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- Construct and solve a medium-scale **RI** model
- Estimate **RI** model on mon. policy IRFs [RW, CEE, CET, ARS, ...]

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 - indirect estim: no formal comparison test, many untargeted shocks
 - direct estim: formal comparison test, noisy set of empirical IRFs

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- Given a solution, re-solving at nearby params is “cheap” → MCMC feasible!

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- **What do we learn** from this exercise?

R1. today, **RI** $\approx$ **NK** iff capital is subject to a real friction (here **capital adj. costs**)

- RI alone matches the data when there is no capital [Maćkowiak-Wiederholt 2015]
- capital adj. costs needed for sluggish I in partial eq. [MWY 2022, Zorn 2018]

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R2. **RI** responses: prompt to idiosyncratic shocks + slow to aggr. shocks

Understanding R1: a contractionary mon. policy shock

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adj. costs make I^* slow

RI makes I^{RI} **hump-shaped!**

This paper brings together three literatures

1. Information frictions (in macro)

- **rational inattention:** Sims 1998, 2003, Maćkowiak-Wiederholt 2015, 2023, Afrouzi-Yang 2021, Miao-Wu-Young 2022, Song-Stern 2025
- **others:** Lucas 1972, Mankiw-Reis 2002, Woodford 2003, Lorenzoni 2009 ...

2. Estimation of medium-scale DSGE models

- **limited info:** Chernozhukov-Hong 2003, Christiano-Eichenbaum-Evans 2005, Christiano-Eichenbaum-Trabandt 2015, Inoue-Shintani 2018, ...
- **full info:** Smets-Wouters 2007, Justiniano-Primiceri-Tambalotti 2010, 2011, ...

3. Micro-macro fit

- Nimark 2007, Maćkowiak-Wiederholt 2009, Boivin-Giannoni-Mihov 2009, Zorn 2018

Outline

1. Putting the RI in RI-DSGE
2. Medium-scale RI-DSGE model
3. Estimation
4. Results
5. Conclusion

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$$x_t^* = G\xi_t$$

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- maximize:

$$\sum_{t=0}^{\infty} \beta^t E_{\iota, -1} \left\{ \underbrace{-\frac{1}{2} (x_{\iota t} - x_{\iota t}^*)' \Theta_{\iota} (x_{\iota t} - x_{\iota t}^*)}_{\text{losses from suboptimal actions}} - \underbrace{\lambda_{\iota} \left[\overbrace{H(\xi_t | \mathcal{I}_{\iota, t-1})}^{\text{uncertainty reduction}} - H(\xi_t | \mathcal{I}_{\iota t}) \right]}_{\text{attention cost}} \right\}$$

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$$S_{\iota t} = \Gamma \xi_t + \nu_{\iota t}, \quad \nu_{\iota t} \sim \mathcal{N}(0, \Sigma_{\nu}) \quad \Rightarrow \quad \mathcal{I}_{\iota t} = \{S_{\iota 0}, \dots, S_{\iota t}\}$$

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- noisy signals $\Rightarrow \xi_t$ innovations learned gradually; actions chosen optimally wrt $\mathcal{I}_{\iota t}$

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- aggregation: idiosyncratic noise washes out; **average responses are sluggish**

RI: one source of inertia that binds every action

For a given λ_ℓ , **three forces** determines the precision of $E_t[x_{\ell t}^* | \mathcal{I}_{\ell t}]$:

- **direct stakes**: the entries of Θ_ℓ
 - larger $\Theta_{\ell,nn} \Rightarrow$ bigger loss from mistracking the n^{th} element of $x_{\ell t}^*$

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$\Rightarrow x_{\iota t} = E_t[x_{\iota t}^*|\mathcal{I}_{\iota t}]$; depend on Θ_ι and the **covariance matrix** of $x_{\iota t}^*$

- Θ_ι : derived from the microfoundations (curvature of profits/utility losses)
- $x_{\iota t}^*$: FOCs (GE endogenous feedback)

Medium-scale RI-DSGE model

Model overview

- Discrete time with aggregate and idiosyncratic shocks
- Paying attention to each shock is a different activity
- Households consume c_{jt} , set a wage w_{jt} and invest in a mutual fund q_{jt} and bonds b_{jt}
- Firms choose capital k_{it} and set a price p_{it}
- Households and firms are subject to **RI**
 - 2nd-order log approx. of their intertemporal objectives $\rightarrow \Theta_\iota$
 - change of variable $\rightarrow x_{\iota t}^*$ (pure tracking problem)
- Standard policy side with a govt balanced budget and inertial Taylor rule

Households' problem

- Optimal actions reduce to:

$$x_{jt}^* = \begin{cases} c_{jt}^* = E_{jt}[c_{jt+1}^*] - \frac{1}{\gamma} E_{jt}[r_t - \pi_{t+1}] \\ w_{jt}^* = \frac{1}{1+\psi\vartheta_w} [\psi l_t + \psi\vartheta_w w_t + \gamma c_{jt}^*] \end{cases}$$

- Loss matrix:

$$\Theta_j = C^{1-\gamma} \begin{bmatrix} \underbrace{\gamma}_{=1} & 0 \\ 0 & \underbrace{\vartheta_w \omega_W (1 + \vartheta_w \psi)}_{49.1} \end{bmatrix}$$

Firms' problem

- Optimal actions reduce to:

$$x_{it}^* = \begin{cases} \zeta_{it}^* = p_t + \frac{(1-\alpha)y_t + \alpha w_t}{\vartheta_p + \alpha(1-\vartheta_p)} & \text{(optimal price given } k_{it-1}) \\ k_{it}^* = \alpha E_{it} \left[w_{t+1} + \frac{1}{\alpha} y_{t+1} - \frac{(r_t - \pi_{t+1})}{1-\beta(1-\delta)} \right] \\ \tilde{k}_{it}^* = k_{it-1}^* + \nu^* k_{it}^* & \text{(adj. cost weighted optimal capital)} \end{cases}$$

- Loss matrix:

$$\Theta_i = C^{-\gamma} Y \begin{bmatrix} \frac{\vartheta_p(\vartheta_p + \alpha(1-\vartheta_p))}{\underbrace{\alpha}_{=24}} & 0 \\ 0 & \underbrace{\frac{\beta\phi[\vartheta_p(1-\alpha-\phi) + \alpha + \phi]}{\vartheta_p + \alpha(1-\vartheta_p)}}_{=0.12} + \underbrace{\frac{\beta\phi(1+\beta)\chi_k}{1-\beta(1-\delta)}}_{\approx 284} \end{bmatrix}$$

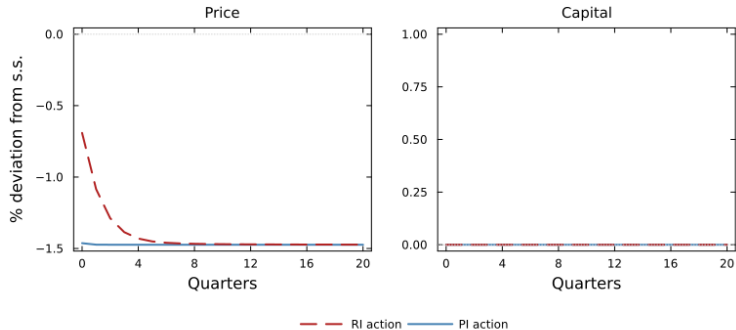
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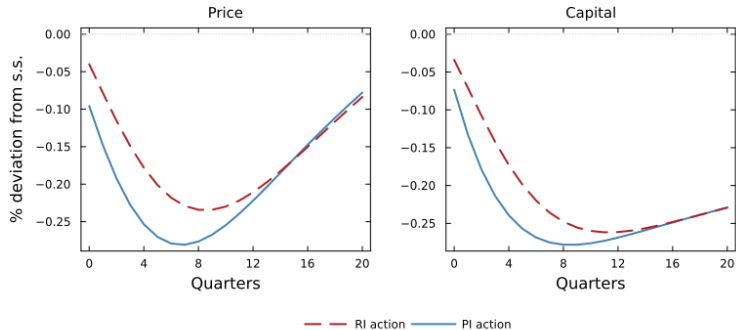
Equilibrium

Firms at iter=1; mon. policy shock starting from the full-info solution



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- **Representation:** min. # of stoch. processes entering hhs and firms problems (IRFs)
 - $\mathcal{J}_{endo} = \{\mathcal{J}_c, \mathcal{J}_{inv}, \mathcal{J}_{inf}, \mathcal{J}_w\}$
 - $\mathcal{J}_{exo} = \{\mathcal{J}_m, \dots\}$

Estimation

Three-step indirect estimation: RI vs NK

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3. Limited info estimation (quasi-Bayesian) of the **RI** model on the **NK** mon. policy IRFs
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 - **reuse the posterior mode's solution to warm start new proposals** ($\approx 2\text{sec}$)

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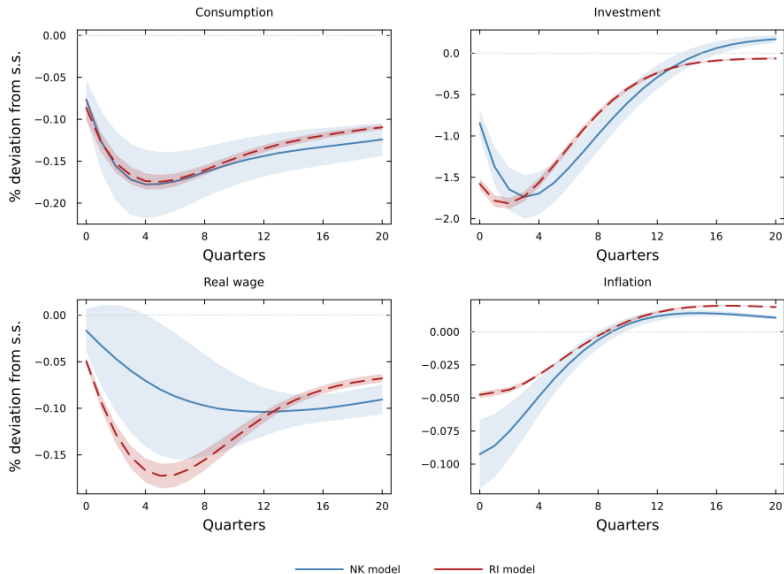
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$\Rightarrow$ Posterior dist. of the mon. policy IRFs

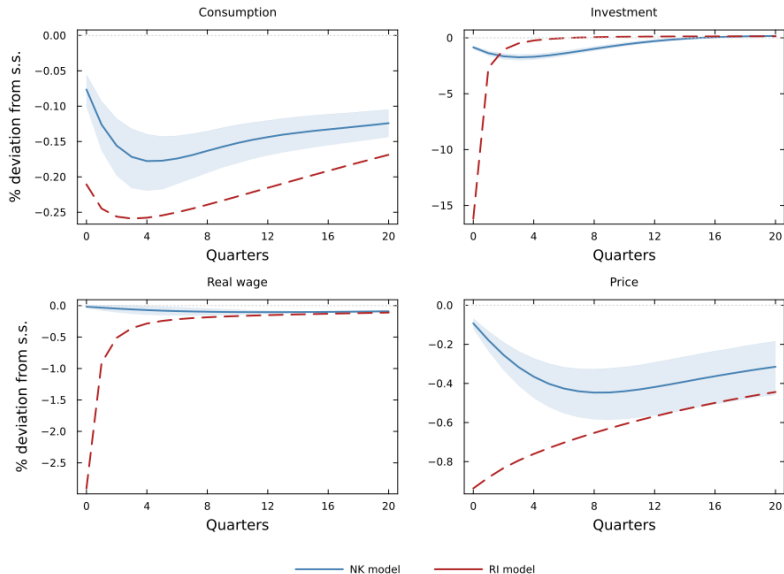
- directly comparable: models share the same core **and** stoch. processes
- step 2's uncertainty is accounted for in step 3
- 6 untargeted shocks

Results

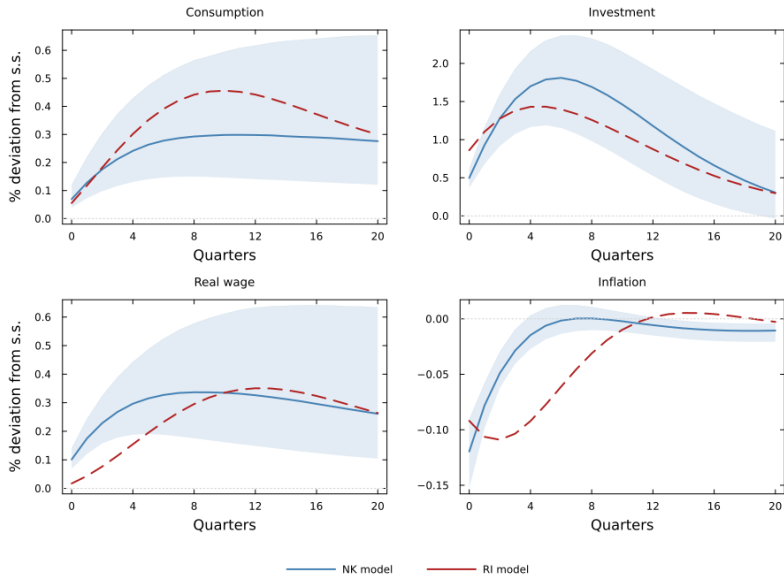
Model's fit: $RI \approx NK$ for mon. policy shock



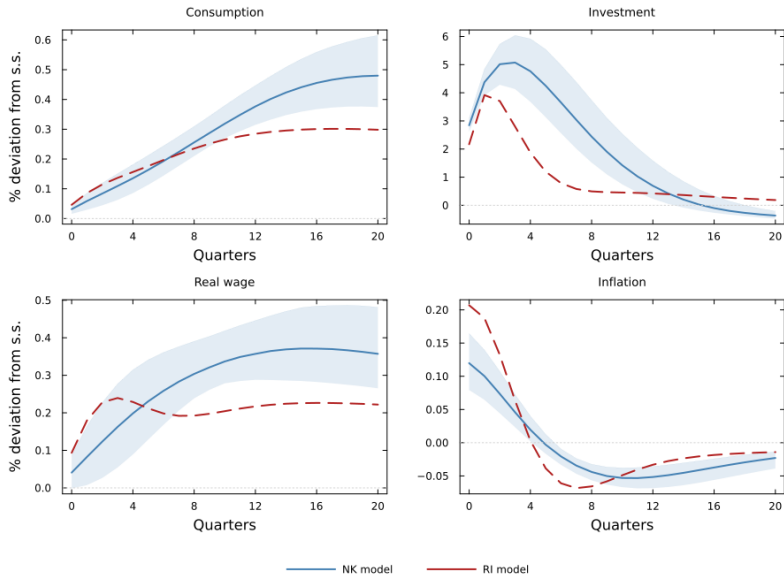
Capital adj. costs are essential for the fit: $\chi_K = 0$



Untargeted shock: TFP



Untargeted shock: MEI



Conclusion

$$\text{RI} + \underbrace{\text{capital adj. costs}}_{\text{proxy for?}} \approx \underbrace{(\text{habits} + \text{Calvo} + \text{inv. adj. costs})}_{\text{adj. frictions (NK core)}}$$

$$\text{RI} + \underbrace{\text{capital adj. costs}}_{\text{proxy for?}} \approx \underbrace{(\text{habits} + \text{Calvo} + \text{inv. adj. costs})}_{\text{adj. frictions (NK core)}}$$

⇒ maybe not *more* frictions, but *better* microfoundations

Thank you!